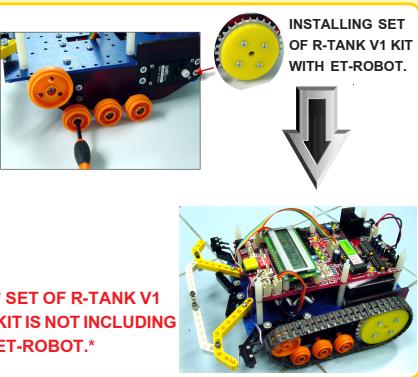


R-TANK V1 KIT

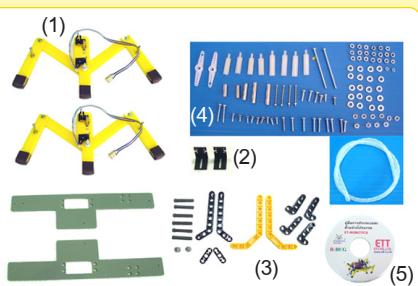
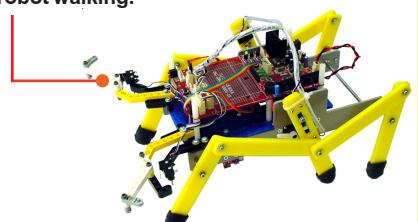
(P-ET-A-00149)

MODIFY ET-ROBOT RD2, 877,
STAMP P40, LOGO 877**R-TANK V1 KIT** is a set for modify ET-ROBOT of ETT. There's accessories to modify tank with machine belt to movable well and accessories of buffer to modify with

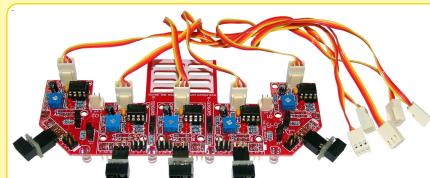
- SET OF ET-ROBOT RD2, 877, STAMP P40, LOGO 877

**R-BUG V1 KIT**

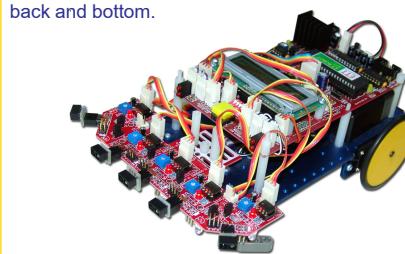
(P-ET-A-00178)

MODIFY ET-ROBOT RD2, 877, STAMP P40,
LOGO877**R-BUG V1 KIT** is a set for modify ET-ROBOT of ETT. To modify as BUG with 6 legs and SW for test its walk and set of BUFFER LEGO.When users installed set of **R-BUG V1 KIT** with ET-ROBOT, it is Robot with 6 legs. Be able to study writing program to control robot walking.**R-SENSOR 5**

(P-ET-A-00314)

It's **R-OFA 5** Channel with 5 SENSOR (R-REFLEX S5) that is designed to interface with ETT Robot. There's R to adjust signal level from signal Analog to TTL Output and 5 of 3PIN ROBOT Cable. It can be used to be electronic buffer; moreover, it can modify SENSOR types to be light (R-LIGHT) and sound (R-SOUND).

- There are three positions to install R-SENSOR 5 with ET-ROBOT; front, back and bottom.



- R-SENSOR 5 can be applied for moving by light, moving by signal REMOTE IR, moving without falling, moving without crashing and moving by sound.

R-REFLEX S5

(P-ET-A-00315)



It is an extra REFLEX SENSOR that can be applied up to 8 cm. long distance.

R-LIGHT S5

(P-ET-A-00316)



It is a light SENSOR with R that can adjust the brightness of light and configure Robot moving by light.

R-SOUND S5

(P-ET-A-00317)

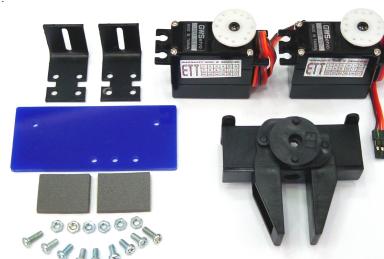


It is a sound SENSOR to detect sound volume by using Microphone to receive audio signal and configure ROBOT moving by sound.

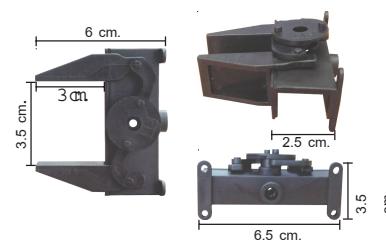
ET-ROBOT GRIP SET

(P-ET-A-00189)

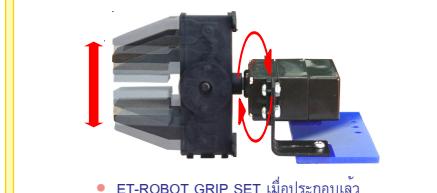
GRIP IS CONTROLLED BY SERVO MOTOR AND MOVABLE WITH 2 AXLES

**ET-ROBOT GRIP SET** is grip is controlled by SERVO MOTOR and be able to move with 2 axles. Grip is made of black plastic and is designed to use with 2 SERVO MOTOR for controlling grip. One SERVO MOTOR runs for IN/OUT of grip and one SERVO MOTOR runs for turn axle. There's plate for attach with ETT robot directly and is able to connect with ET-ROBOT RD2, 877, LOGO 877, STAMP P40 or adapt for mechanic arms well.**ET-ROBOT GRIP SET INCLUDES;**

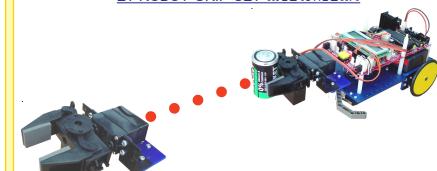
1. R-SERVO GRIP 1 PIECE
2. SERVO MOTOR S03T/STD/JR 2 PIECES
3. PLASTIC PLATE FOR ATTACH ET-ROBOT AND R-SERVO MOUNT
4. CD-ROM

**SIZE AND DISTANCE OF GRIP**

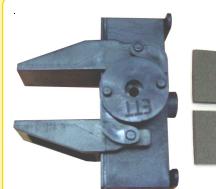
- WIDEST 3.5 CM.
- DEEPEST 3 CM.
- GRIP SIZE NOT INCLUDING SERVO MOTOR (LxWxH) 6cm. x 6.5cm. x 3.5cm.
- WEIGHT NOT INCLUDING SERVO MOTOR 0.02 kg.
- WEIGHT INCLUDING SERVO MOTOR 0.12 kg.
- BE ABLE TO CONTAIN 0.5kg. WITH MOVABLE BY AXLE



• ET-ROBOT GRIP SET เมื่อปรับกnob เล็ก

**R-SERVO GRIP**

(A-MO-M-00076)



There's only plastic GRIP not including SERVO MOTOR and be able to connect with 2 SERVO MOTOR for S03T, S03N, S03NXF, FUTABA S3003